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Textbook reference for lectures 1-13 is . Applied Nonlinear Control, Slotine and Li, Prentice-Hall 1991. Main references for lectures 14-20 are . R1 Lohmiller, W., and Slotine, J.J.E., "On Contraction Analysis for Nonlinear Systems," Automatica, 34(6), 1998 R2 Slotine, J.J.E., "Modular Stability Tools for Distributed Computation and Control," Int. J. Adaptive Control and Signal Processing, 17(6 ...

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Applied Nonlinear Control by Jean-Jacques Slotine

Professor Jean-Jacques Slotine is Professor of Mechanical Engineering and Information Sciences, Professor of Brain and Cognitive Sciences, and Director of the Nonlinear Systems Laboratory. He received his Ph.D. from the Massachusetts Institute of Technology in 1983, at age 23. After working at Bell Labs in the computer research department, he joined the faculty at MIT in 1984.

## JEAN-JACQUES SLOTINE

Slotine minimizes a lot of that dense math and, in my opinion, focuses on the important concepts of nonlinear control without getting bogged down. On the negative side, as others have pointed out, Slotine's book doesn't have the detailed mathematical treatment of other books on nonlinear control.

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He is the coauthor of the textbooks Robot Analysis and Control (Wiley, 1986) and Applied Nonlinear Control (Prentice-Hall, 1991). Prof. Slotine was a member of the French National Science Council from 1997 to 2002, and of Singapore's A\*STAR SigN Advisory Board from 2007 to 2010.

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